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Textbook reference for lectures 1-13 is . Applied Nonlinear Control, Slotine and Li, Prentice-Hall 1991. Main references for lectures 14-20 are . R1 Lohmiller, W., and Slotine, J.J.E., "On Contraction Analysis for Nonlinear Systems," Automatica, 34(6), 1998 R2 Slotine, J.J.E., "Modular Stability Tools for Distributed Computation and Control," Int. J. Adaptive Control and Signal Processing, 17(6 ...

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From (6.2) and (6.3), design. the actual input flow is determined by the nonlinear control - The central idea of the approach is to algebraically law transform a nonlinear system dynamics in to a fully or partly one, so that the linear control theory can be applied.

Applied Nonlinear Control | Control Theory | Nonlinear System

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Analysis and Control” (Asada and Slotine, Wiley, 1986), and “Applied Nonlinear Control” (Slotine and Li, Prentice-Hall, 1991) and is one of the most cited researcher in both systems science and robotics. He was a member of the French National Science Council from 1997 to 2002, and a member of Singapore’s

JEAN-JACQUES SLOTINE - Mechanical Engineering

Constructive nonlinear control - Sepulchre et al. - Springer, 1997 More focused on passivity and recursive approaches Nonlinear control systems - A. Isidori - Springer Verlag, 1995 A reference for geometric approach Applied Nonlinear control - J.J. Slotine and W. Li - Prentice-Hall, 1991 An interesting reference in particular for sliding mode

Control of Nonlinear Systems - Gipsa-lab

Nonlinear System Analysis Lyapunov Based Approach Lecture 4 Module 1 ... Applied Nonlinear Control, J. J. E. Slotine and W. Li, Prentice Hall 3. Nonlinear System Analysis, M. Vidyasagar, Second Edition, Prentice Hall ... solutions of are globally uniformly bounded and satisfy OPQ A S[

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